

Antenna Positioning System APTL & EAP

Our innovative OTA/CTIA positioning systems were especially developed for the smooth and accurate positioning of devices and antennas during tests. Both can be positioned in linear axes (vertical and horizontal) and in rotation axes (elevation, azimuth, tilt and polarisation), depending on customer requirements.



- Consists of an APTL (Azimuth Polarization Tilt Linear Positioner) and an EAP (Electrical Antenna Positioner) mounted on linear rails
- Spherical Great-Circle Cut system
- High accurate antenna measurement capabilities for both, near-field and far-field data acquisition
- 5G NR FR1 / FR2 OTA testing capabilities
- Accuracy enough for a frequency coverage up to 90 GHz
- Ideal for Antenna-Under-Test (AUT) like satellite dishes or massive MIMO base stationantennas
- Independent rotations of all motion axis
- Variable speed adjustments at all axis
- Readout by high accurate encoders
- Integrated rotary joint for EUT and antennas available upon request
- Easy installation and implementation in existing chambers

Information presented enclosed is subject to change as product enhancements are made regularly. Pictures included are for illustration purposes only and do not represent all possible configurations.



Technical data APTL:

Distance center of gravity of DUT to mounting flange Rotating angle azimuth (x-axis) electrically +/- 90° Speed azimuth adjustable 0.5°/s – 18°/s Rotating angle polarization (y-axis) electrically +/- 60° Speed polarization adjustable 0.5°/s – 30°/s Polarization axis height above floor 1.75 m Tilting angle (z-axis) electrically -45 ° (down) to +60° (up) Speed tilting adjustable 0.5°/s – 18°/s Positioning accuracy in each axis +/- 0.05° Linear movement range manually (manually lockable) Positioning accuracy linear +/- 1 mm (indicated by scale) Mounted on linear rails for manual distance adjustment Wooden plates for absorber mounting Absorbers for covering	Load capability	max. 50 kg
Rotating angle azimuth (x-axis) electrically Speed azimuth adjustable Rotating angle polarization (y-axis) electrically Speed polarization adjustable Polarization axis height above floor Tilting angle (z-axis) electrically Speed tilting adjustable Positioning accuracy in each axis Linear movement range manually (manually lockable) Positioning accuracy linear Mounted on linear rails for manual distance adjustment H 90° 0.5°/s – 18°/s H 60° 1.75 m 1.75 m 1.75 m -45° (down) to + 60° (up) 0.5°/s – 18°/s +/- 0.05° 500 mm +/- 1 mm (indicated by scale) approx. 600 mm Wooden plates for absorber mounting	Distance center of gravity of DUT to mounting	max. 150 mm
Speed azimuth adjustable Rotating angle polarization (y-axis) electrically Speed polarization adjustable Polarization axis height above floor Tilting angle (z-axis) electrically Speed tilting adjustable Positioning accuracy in each axis Linear movement range manually (manually lockable) Positioning accuracy linear Mounted on linear rails for manual distance adjustment O.5°/s – 18°/s 1.75 m 1.75 m 1.75 m 0.5°/s – 18°/s 45° (down) to + 60° (up) 0.5°/s – 18°/s 47- 0.05° 500 mm 47- 1 mm (indicated by scale) approx. 600 mm Wooden plates for absorber mounting	flange	
Rotating angle polarization (y-axis) electrically Speed polarization adjustable Polarization axis height above floor Tilting angle (z-axis) electrically Speed tilting adjustable Positioning accuracy in each axis Linear movement range manually (manually lockable) Positioning accuracy linear Mounted on linear rails for manual distance adjustment +/- 60° 0.5°/s – 30°/s 1.75 m -45 ° (down) to + 60° (up) 0.5°/s – 18°/s +/- 0.05° 500 mm +/- 1 mm (indicated by scale) approx. 600 mm Wooden plates for absorber mounting	Rotating angle azimuth (x-axis) electrically	+/- 90°
Speed polarization adjustable Polarization axis height above floor Tilting angle (z-axis) electrically Speed tilting adjustable Positioning accuracy in each axis Linear movement range manually (manually lockable) Positioning accuracy linear Mounted on linear rails for manual distance adjustment O.5°/s – 30°/s 1.75 m -45 ° (down) to + 60° (up) 0.5°/s – 18°/s +/- 0.05° 500 mm +/- 1 mm (indicated by scale) approx. 600 mm Wooden plates for absorber mounting	Speed azimuth adjustable	0.5°/s – 18°/s
Polarization axis height above floor Tilting angle (z-axis) electrically Speed tilting adjustable Positioning accuracy in each axis Linear movement range manually (manually lockable) Positioning accuracy linear Mounted on linear rails for manual distance adjustment 1.75 m -45 ° (down) to + 60° (up) 0.5°/s – 18°/s +/- 0.05° 500 mm +/- 1 mm (indicated by scale) approx. 600 mm Wooden plates for absorber mounting	Rotating angle polarization (y-axis) electrically	+/- 60°
Tilting angle (z-axis) electrically Speed tilting adjustable Positioning accuracy in each axis Linear movement range manually (manually lockable) Positioning accuracy linear Mounted on linear rails for manual distance adjustment -45 ° (down) to + 60° (up) 0.5°/s - 18°/s +/- 0.05° 500 mm +/- 1 mm (indicated by scale) approx. 600 mm Wooden plates for absorber mounting	Speed polarization adjustable	0.5°/s - 30°/s
Speed tilting adjustable Positioning accuracy in each axis Linear movement range manually (manually lockable) Positioning accuracy linear Mounted on linear rails for manual distance adjustment O.5°/s – 18°/s +/- 0.05° 500 mm +/- 1 mm (indicated by scale) approx. 600 mm Wooden plates for absorber mounting	Polarization axis height above floor	1.75 m
Positioning accuracy in each axis +/- 0.05° Linear movement range manually (manually lockable) 500 mm Positioning accuracy linear +/- 1 mm (indicated by scale) Mounted on linear rails for manual distance adjustment approx. 600 mm Wooden plates for absorber mounting	Tilting angle (z-axis) electrically	-45 ° (down) to + 60° (up)
Linear movement range manually (manually lockable) Positioning accuracy linear +/- 1 mm (indicated by scale) Mounted on linear rails for manual distance adjustment approx. 600 mm Wooden plates for absorber mounting	Speed tilting adjustable	0.5°/s – 18°/s
(manually lockable) Positioning accuracy linear Mounted on linear rails for manual distance adjustment +/- 1 mm (indicated by scale) approx. 600 mm Wooden plates for absorber mounting	Positioning accuracy in each axis	+/- 0.05°
(manually lockable) Positioning accuracy linear +/- 1 mm (indicated by scale) Mounted on linear rails for manual distance adjustment approx. 600 mm Wooden plates for absorber mounting	Linear movement range manually	500 mm
Mounted on linear rails for manual distance adjustment approx. 600 mm Wooden plates for absorber mounting	(manually lockable)	300 11111
adjustment approx. 600 mm Wooden plates for absorber mounting	Positioning accuracy linear	+/- 1 mm (indicated by scale)
·		approx. 600 mm
Absorbers for covering		·
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Accessories Mounting plate for antennas	Accessories	J.
Power supply cable		Power supply cable
Service manual		Service manual

Technical data EAP:

Load capability	max. 5 kg
Rotating angle polarization (y-axis) electrically	+/- 60°
Speed polarization adjustable	0.5°/s – 18°/s
Polarization axis height electrical adjustable	1.3 m - 2.2 m (1.75 m +/- 0.45 m)
Polarization positioning accuracy	+/- 0.05°
Linear movement range (y-axis) electrical	+/- 450 mm
Linear movement range (z-axis) electrical	+/- 450 mm
Speed linear adjustable	1 cm/s – 10 cm/s
Positioning accuracy linear	+/- 1 mm
Mounted on linear rails for electrical distance adjustment	approx. 5.5 m
	Wooden plates for absorber mounting
	Absorbers for covering
Accessories	Mounting plate for antennas
	Power supply cable
	Service manual



Technical data general:

Metal structure
approx. 8.4 m x 1.6 m x 2.6 m
Synchronous servo motors
High accurate gears
380 VAC – 480 VAC, 50 Hz / 60 Hz three phases
max. 32 A
300 mA
Fiber optic lines
LAN (TCP/IP); (IEEE only with NCD)
20 dB under limits DIN EN 55011:2018-05 class B
10° C – 35 ° C
approx. 4300 kg
Wooden plates for absorber mounting Absorbers for covering Mounting plate for antennas Power supply cable Service manual

Other specifications available upon on request